# Temporal HeartNet: Towards Human-Level Automatic Analysis of Fetal Cardiac Screening Video

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MICCAI (12<sup>th</sup> September 2017)

# Congenital Heart Disease (CHD)

- Range of structural heart defects present at birth
- Leading cause of infant mortality
  - ▶ 42% of infant deaths reported to WHO
- Heart examination during routine second trimester abnormality screening using **2D ultrasound**
- Multiple viewing planes
- Highly skilled

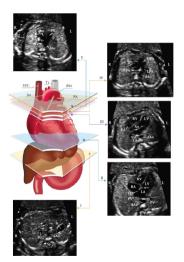


Figure: Source: ISUOG

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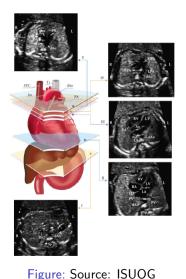
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#### Aim

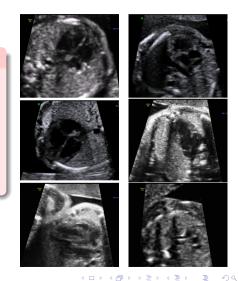
Can automated methods assist in analysing this video?



# Challenges

#### Challenges

- Unconstrained video stream
- Unpredictable probe/fetal movement
- Variable orientation
- Imaging artefacts (speckle, shadowing, enhancement)
- Low contrast and indistinct structures

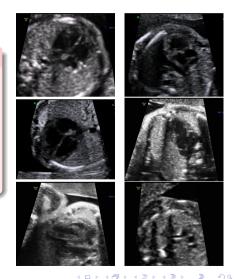


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• How can we make sense of this raw video data?



- Interpret the video stream
- Estimate key low-level variables of interest:

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- Estimate key low-level variables of interest:
  - Heart Visibility,  $h_t \in \{0, 1\}$
  - 2 Heart Centre Position,  $\mathbf{x}_t \in \mathbb{R}^2$
  - **3** View Label,  $v_t \in \{4C, LVOT, 3V\}$ 
    - ★ Four chamber
    - ★ Left Ventricular Outflow Tract
    - ★ Three vessels
  - ( Heart Orientation,  $\theta_t \in [0, 2\pi)$
  - **(5)** Heart Radius,  $r_t \in \mathbb{R}^+$

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#### Summary

Find a basic 'global coordinate system' for each frame

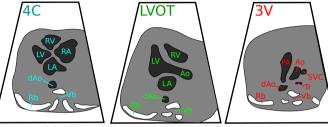
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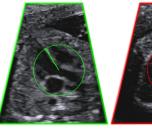
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• Prior work based on particle-filtering model (Bridge et al. 2017)

## Viewing Plane Definitions



LV/RV left/right ventricle, LA/RA left/right atrium, (d)Ao (descending) aorta, PA pulmonary artery, SVC superior vena cava, Tr trachea, Vb vertebra, Rb ribs

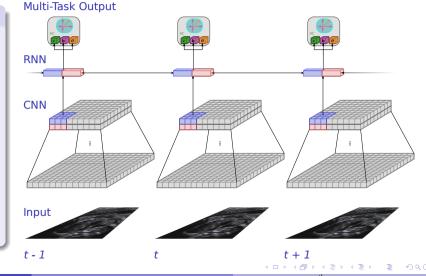




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#### Components

- Spatial CNN (VGG-16)
- Temporal RNN (BLSTM)
- Multi-task Layers:
  - View
  - Location
  - Orientation
  - Radius
- Two alternatives:
   Circular anchors
   IoU



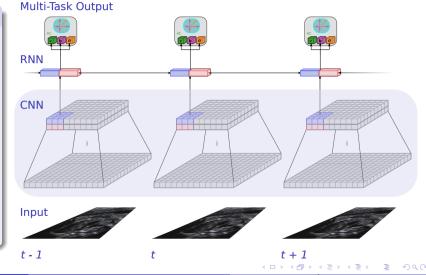
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Temporal HeartNet

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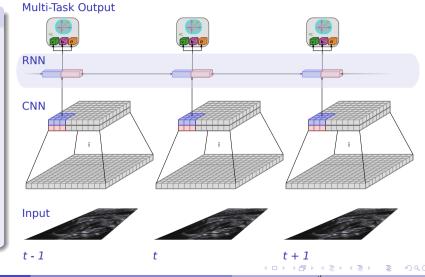
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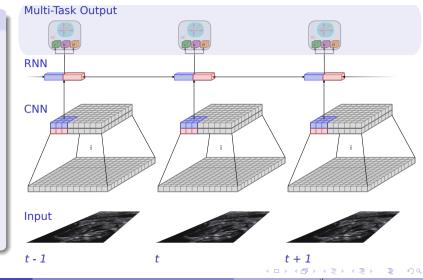
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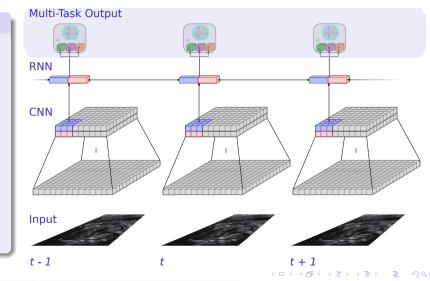
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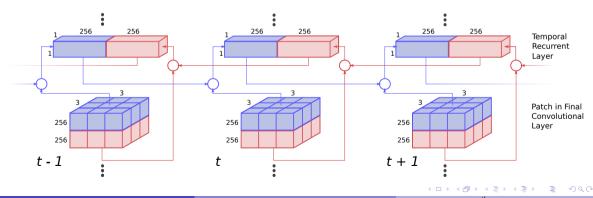
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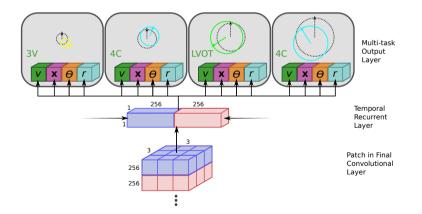
# **Bi-directional LSTM RNN**

- Recurrent 512-D representation for an image region
- LSTM (long short-term memory) cells learn long-term dependencies
- Parameters shared between image regions
- Bi-directional: Two separate 256-D recurrent vectors: one forwards, one backwards



### Multi-Task Prediction Architecture 1: 'Circular Anchors'

 Independently predict offsets from four *circular anchors* with radii {80, 120, 160, 240} (Ren et al. 2015, "Faster R-CNN")



## Training – Circular Anchor Architecture

- Loss functions:
  - L<sub>cls</sub> Classification (v): Softmax
  - $L_{loc}$  Localisation  $(\mathbf{x}, \theta, r)$ : Smooth- $I_1$  loss
  - Total:

 $L = L_{cls} + \lambda_1 L_{loc}$ 

- 31

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- Training samples:
  - ▶ **Positives:** Anchors with ground-truth IoU overlap > 0.7
  - ▶ Negatives: Anchors with ground-truth IoU overlap < 0.5
  - **Excluded:** Anchors with 0.5 < IoU < 0.7

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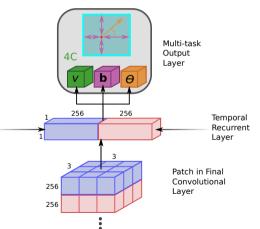
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  - **Excluded:** Anchors with 0.5 < IoU < 0.7
- Location, orientation and radius gradients only applied for positive anchors

## Multi-Task Prediction Architecture 2: 'IoU'

- $\bullet$  Regress top, bottom, left, and right edges of bounding box (b) with IoU loss
- Orientation is regressed separately



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## Training – IoU Architecture

- Loss functions:
  - L<sub>cls</sub> Classification (v): Softmax
  - Localisation (b): IoU (intersection over union)
  - $L_{ori}$  **Orientation** ( $\theta$ ): Cosine loss

$$L_{
m ori} = 1 - \cos\left(\hat{ heta} - heta
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Total:

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- Database of 91 videos from 12 healthy subjects
- Multiple views and range of gestational ages (20-35 weeks), orientations, magnifications
- Leave-one-subject-out cross-validation
- Pre-trained VGG-16 or random initialisation

# Example Output

#### Output

#### **Ground Truth**

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## Results

Method	Class Error <i>or</i> Outside 0.25 <i>î</i> (%)*	Class Error <i>or</i> IoU < 0.25 (%)	Orient. Error <sup>†</sup>
<b>Circular Anchor</b>	28.8	30.3	0.074
IoU Loss	26.8	28.7	0.084
RNN + Circular Anchor	<u>21.6</u>	<u>27.7</u>	<u>0.072</u>

\* Estimated inter-rater variation: 26%, intra-rater variation: 15%

$$^{\dagger}$$
 Orientation Error  $=rac{1}{2}\left(1-\cos\left( heta-\hat{ heta}
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## Conclusions

- Deep architecture for predicting basic information in each frame of fetal cardiac screening video
- Three parts:
  - CNN
  - Spatially-localised RNN
  - Multi-task output
- Approaching human-level accuracy on highly ambiguous problem
- IoU architecture gives better localisation than circular anchors
- RNN significantly improves results

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## Thank You

- Christos Ioannou, John Radcliffe Hospital, Oxford
- EPSRC 'Seebibyte' Programme Grant (EP/M013774/1)
- EPSRC Doctoral Training Award

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